# **Probability Functional Descent:** A Unifying Perspective on GANs, VI, and RL

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#### **Generative adversarial networks**



#### Variational inference



#### **Reinforcement learning**

 $\pi$ 





## Lots of algorithms...

#### **Generative adversarial networks**

- Minimax GAN
- Non-saturating GAN
- Wasserstein GAN
- f-GAN

#### Variational inference

- Black-box variational inference
- Adversarial variational Bayes

#### **Reinforcement learning**

- Policy iteration/Q-learning
- REINFORCE
- Deep deterministic policy gradient
- Dual actor-critic
- Soft actor-critic

## Lots of algorithms... but same "under the hood"!

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## They all minimize *probability functionals*

**Generative adversarial networks** 

Variational inference

 $J_{ ext{GAN}}(\mu) = D(\mu \,||\, 
u_0)$ 

$$J_{ ext{VI}}(q) = D_{ ext{KL}}(q( heta) \,|| \, p( heta | x))$$



They all minimize *probability functionals* 

# $J:\mathcal{P}(X) ightarrow\mathbb{R}$

## **Probability distributions over elements in X** (in the GAN setting: generators of images)

$$f: \mathbb{R}^n o \mathbb{R} \qquad \qquad x_{ ext{new}} \leftarrow x_0 - lpha 
abla f(x_0)$$

$$f_{ ext{linear}}(x) = f(x_0) + (x-x_0) \cdot 
abla f(x_0)$$

$$f(x)pprox f_{ ext{linear}}(x)=f(x_0)+(x-x_0)\cdot 
abla f(x_0)$$

Gradient descent says: **if we move** *x* **such that** *f*<sub>linear</sub> **decreases, hopefully** *f* **will decrease as well** 



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 $x_{ ext{new}} \leftarrow x_0 - lpha 
abla f(x_0)$ 

$$egin{aligned} f_{ ext{linear}}(x_{ ext{new}}) &= f(x_0) + (x_0 - lpha 
abla f(x_0) - x_0) \cdot 
abla f(x_0) \ &= f(x_0) - lpha || 
abla f(x_0) ||^2 \ &\leq f_{ ext{linear}}(x_0) \end{aligned}$$

$$f(x) pprox f_{ ext{linear}}(x) = f(x_0) + (x - x_0) \cdot 
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Gradient descent says: **if we move** *x* **such that** *f*<sub>linear</sub> **decreases, hopefully** *f* **will decrease as well** 

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abla f(x_0) ||^2 \ &\leq f_{ ext{linear}}(x_0) \end{aligned}$$

$$f(x) \approx f_{\text{linear}}(x) = f(x_0) + (x - x_0) \cdot \nabla f(x_0)$$

#### Gradient descent says: **find** *x*<sub>**new**</sub> **such that**

$$x_{ ext{new}} \cdot 
abla f(x_0) \leq x_0 \cdot 
abla f(x_0)$$

$$egin{aligned} f(x) &pprox f(x_0) + 
abla f(x_0) \cdot (x-x_0) \ &J(\mu) &pprox J(\mu_0) + \int 
abla J(\mu_0) \, d(\mu-\mu_0) \, d(\mu-\mu_0) \ \end{aligned}$$

$$J:\mathcal{P}(X)
ightarrow\mathbb{R}\qquad 
abla J(\mu_0):X
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$$egin{aligned} f(x) &pprox f(x_0) + 
abla f(x_0) \cdot (x-x_0) \ &J(\mu) &pprox J(\mu_0) + \int 
abla J(\mu_0) \, d(\mu-\mu_0) \ &= J(\mu_0) + \mathbb{E}_{x \sim \mu}[
abla J(\mu_0)(x)] - \mathbb{E}_{x \sim \mu_0}[
abla J(\mu_0)(x)] \end{aligned}$$

$$J:\mathcal{P}(X) o\mathbb{R} \qquad 
abla J(\mu_0):X o\mathbb{R}$$

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abla J(\mu_0)(x)] \ &= \mathbb{E}_{x \sim \mu} [
abla J(\mu_0)(x)] + ext{const.} \end{aligned}$$

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$$J:\mathcal{P}(X) o\mathbb{R}\qquad 
abla J(\mu_0):X o\mathbb{R}$$

von Mises influence function

## Probability functional descent

- 1. Compute or approximate  $\nabla J(\mu_0)$
- 2. Find a distribution  $\mu$  such that

$$\mathbb{E}_{x\sim\mu}[
abla J(\mu_0)(x)] \leq \mathbb{E}_{x\sim\mu_0}[
abla J(\mu_0)(x)]$$

$$J:\mathcal{P}(X)
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2 (in practice). Parameterize  $\mu$  with  $\theta$  and take a gradient descent step on the function

$$heta\mapsto \mathbb{E}_{x\sim \mu_ heta}[
abla J(\mu_{ heta_0})(x)]$$

## Probability functional descent

- 1. Compute or approximate  $\,\, 
  abla J(\mu_0)$
- 2. Find a distribution  $\mu$  such that

$$\mathbb{E}_{x\sim\mu}[
abla J(\mu_0)(x)] \leq \mathbb{E}_{x\sim\mu_0}[
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1 (in practice). Fit a neural network to  $\nabla J(\mu_0): X \to \mathbb{R}$ 2 (in practice). Parameterize  $\mu$  with  $\theta$  and take a gradient descent step on the function Neural network

$$heta\mapsto \mathbb{E}_{x\sim \mu_ heta}[
abla J(\mu_{ heta_0})(x)]$$

## PFD for **minimax GANs**

$$J(\mu)=D_{
m JS}(\mu||
u_0)$$

$$abla J(\mu)(x) = rac{1}{2}\lograc{\mu(x)}{\mu(x)+
u_0(x)}$$

- 1. Compute or approximate  $\nabla J(\mu_0)$
- 2. Take a gradient descent step on  $\ heta\mapsto \mathbb{E}_{x\sim \mu_{ heta}}[
  abla J(\mu_{ heta_0})(x)]$

## PFD for minimax GANs

2) Take a gradient step on the generator

$$heta \mapsto \mathbb{E}_{x \sim \mu_ heta}[rac{1}{2}\log D(x)]$$

- 1. Compute or approximate  $\nabla J(\mu_0)$
- 2. Take a gradient descent step on  $\ heta\mapsto \mathbb{E}_{x\sim \mu_ heta}[
  abla J(\mu_{ heta_0})(x)]$

## PFD for variational inference

$$egin{aligned} J(q) &= D_{ ext{KL}}(q(z) \,||\, p(z|x)) \ 
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onumber \ \nabla J(q)(z) &= \log rac{q(z)}{p(x|z)\, p(z)} \end{aligned}$$

- 1. Compute or approximate  $\nabla J(\mu_0)$
- 2. Take a gradient descent step on  $\ heta\mapsto \mathbb{E}_{x\sim \mu_ heta}[
  abla J(\mu_{ heta_0})(x)]$

## PFD for variational inference

$$egin{aligned} J(q) &= D_{ ext{KL}}(q(z) \,|| \, p(z|x)) \ 
onumber 
onumbe$$

1) We can compute this exactly, no need to fit a network to it

2) Take a gradient step on the ELBO

$$heta \mapsto \mathbb{E}_{z \sim q_ heta} \Big[ \log rac{q_{ heta_0}(z)}{p(x|z)\,p(z)} \Big]$$

- 1. Compute or approximate  $\nabla J(\mu_0)$
- 2. Take a gradient descent step on  $\ heta\mapsto \mathbb{E}_{x\sim \mu_ heta}[
  abla J(\mu_{ heta_0})(x)]$

## PFD for actor-critic RL algorithms

$$J(\pi) = -\mathbb{E} \Big[ \sum_{t=0}^\infty \gamma^t R_t \Big]$$

$$abla J(\pi)(s,a) = -(1-\gamma)ig(Q^{\pi}(s,a)-V^{\pi}(s)ig)$$

- 1. Compute or approximate  $\nabla J(\mu_0)$
- 2. Take a gradient descent step on  $\ heta\mapsto \mathbb{E}_{x\sim \mu_ heta}[
  abla J(\mu_{ heta_0})(x)]$

## PFD for actor-critic RL algorithms

$$J(\pi) = -\mathbb{E}\Big[\sum_{t=0}^{\infty} \gamma^t R_t\Big]$$
 1) Fit a neural network to this advantage function (e.g. by minimizing the Bellman residuals)  
 $abla J(\pi)(s,a) = -(1-\gamma)\Big(Q^{\pi}(s,a) - V^{\pi}(s)\Big)$ 

2) Take a gradient step on

$$heta\mapsto -\mathbb{E}_{(s,a)\sim \pi_{ heta}}ig[Q^{\pi_{ heta_0}}(s,a)-V^{\pi_{ heta_0}}(s)ig]$$

- 1. Compute or approximate  $\nabla J(\mu_0)$
- 2. Take a gradient descent step on  $\ heta\mapsto \mathbb{E}_{x\sim \mu_ heta}[
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## PFD for minimax GANs

2) Take a gradient step on the generator

$$heta \mapsto \mathbb{E}_{x \sim \mu_ heta}[rac{1}{2}\log D(x)]$$

- 1. Compute or approximate  $\nabla J(\mu_0)$
- 2. Take a gradient descent step on  $\ heta\mapsto \mathbb{E}_{x\sim \mu_ heta}[
  abla J(\mu_{ heta_0})(x)]$

convex conjugate

# PFD for **any convex function** $J^{\star}(\varphi) = \sup_{\mu \in \mathcal{M}(X)} \int \varphi \, d\mu - J(\mu)$

$$J(\mu) ext{ convex}$$

$$abla J(\mu) = rgmax_{arphi \in \mathcal{C}(X)} \left[ \mathbb{E}_{x \sim \mu} [arphi(x)] - J^{\star}(arphi) 
ight]$$

- 1. Compute or approximate  $\nabla J(\mu_0)$
- 2. Take a gradient descent step on  $\ heta\mapsto \mathbb{E}_{x\sim \mu_ heta}[
  abla J(\mu_{ heta_0})(x)]$

convex conjugate

## PFD for any convex function

- /

1

$$J^\star(arphi) = \sup_{\mu \in \mathcal{M}(X)} \int arphi \, d\mu - J(\mu)$$

$$J(\mu) ext{ convex}$$
  
1) Fit a neural network by maximizing the inner objective (can use SGD)  
 $abla J(\mu) = rgmax_{arphi \in \mathcal{C}(X)} \left[ \mathbb{E}_{x \sim \mu} [arphi(x)] - J^{\star}(arphi) 
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2) Take a gradient step on

$$heta\mapsto \mathbb{E}_{x\sim \mu_ heta}[arphi(x)]$$

- 1. Compute or approximate  $\nabla J(\mu_0)$
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ight]$ 

Neatly summarized as a minimax game!

$$\inf_{\mu\in\mathcal{P}(X)}\sup_{arphi\in\mathcal{C}(X)}\mathbb{E}_{x\sim\mu}[arphi(x)]-J^{\star}(arphi)$$

2) Take a gradient step on

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- 1. Compute or approximate  $\nabla J(\mu_0)$
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## PFD for Wasserstein GAN

 $egin{aligned} J(\mu) &= W_1(\mu,
u_0) \ & ext{ 1) Fit a neural network by maximizing the inner objective (can use SGD)} \ & 
abla J(\mu) &= rgmax & \left[ \mathbb{E}_{x \sim \mu}[arphi(x)] - J^\star(arphi) 
ight] \end{aligned}$ 

2) Take a gradient step on

$$heta \mapsto \mathbb{E}_{x \sim \mu_ heta}[arphi(x)]$$

- 1. Compute or approximate  $\nabla J(\mu_0)$
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## PFD for Wasserstein GAN

 $J(\mu) = W_1(\mu, \nu_0)$ 

$$J^{\star}(arphi) = egin{cases} \mathbb{E}_{x \sim 
u_0}[arphi(x)] & ext{if } arphi ext{ is 1-Lipschitz} \ \infty & ext{otherwise} \end{cases}$$

1) Fit a neural network by maximizing the inner objective (can use SGD)

$$abla J(\mu) = rgmax_{arphi \in \mathcal{C}(X)} \left[ \mathbb{E}_{x \sim \mu} [arphi(x)] - J^{\star}(arphi) 
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1) Fit a neural network by maximizing the inner objective (can use SGD)

$$abla J(\mu) = rgmax_{arphi \in \mathrm{Lip}_1(X)} \Big[ \mathbb{E}_{x \sim \mu} [arphi(x)] - \mathbb{E}_{x \sim 
u_0} [arphi(x)] \Big]$$

2) Take a gradient step on

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Gradient descent

in the space of

probability

distributions!